Faster isomorphism testing of p-groups of Frattini class 2

Speaker: Chuanqi Zhang

Joint with Gábor Ivanyos, Euan Mendoza, Youming Qiao, and Xiaorui Sun

Centre for Quantum Software and Information University of Technology Sydney, Australia

Theory of Computing Seminar at the University of Wisconsin-Madison November 1, 2024



Faster isomorphism testing of p-groups of Frattini class 2

Speaker: Chuanqi Zhang

Joint with Gábor Ivanyos, Euan Mendoza, Youming Qiao, and Xiaorui Sun

Centre for Quantum Software and Information University of Technology Sydney, Australia

Theory of Computing Seminar at the University of Wisconsin-Madison November 1, 2024



This work has been accepted to FOCS 2024 and invited to the SICOMP special issue.

• Background of finite group isomorphism.

- From *p*-group isomorphism to 3-tensor isomorphism.
- Our main results and an overview of our algorithm.
- Summary and further directions.



- Background of finite group isomorphism.
- From *p*-group isomorphism to 3-tensor isomorphism.
- Our main results and an overview of our algorithm.
- Summary and further directions.



- Background of finite group isomorphism.
- From *p*-group isomorphism to 3-tensor isomorphism.
- Our main results and an overview of our algorithm.

• Summary and further directions.



- Background of finite group isomorphism.
- From *p*-group isomorphism to 3-tensor isomorphism.
- Our main results and an overview of our algorithm.
- Summary and further directions.



Given the multiplication tables of two groups of finite order N, determine whether they are isomorphic.

• First algorithm: N^{dog N+O(1)} time attributed to Tarjan [Miller'78]



Given the multiplication tables of two groups of finite order N, determine whether they are isomorphic.



Given the multiplication tables of two groups of finite order N, determine whether they are isomorphic.

			S_2	
		0	e	s
		e	e	s
		s	s	e



Given the multiplication tables of two groups of finite order N, determine whether they are isomorphic.

			S_2	
		0	e	s
		e	e	s
		s	s	e



Given the multiplication tables of two groups of finite order N, determine whether they are isomorphic.



Given the multiplication tables of two groups of finite order N, determine whether they are isomorphic.

- Best known algorithm: $N^{\frac{1}{4} \log N + O(1)}$ time [Rosenbaum'13]
- Open question: $N^{\log N} \xrightarrow{?} N^{o(\log N)}$



Given the multiplication tables of two groups of finite order N, determine whether they are isomorphic.

- First algorithm: $N^{\log N+O(1)}$ time attributed to Tarjan [Miller'78]
- Best known algorithm: $N^{\frac{1}{4} \log N + O(1)}$ time [Rosenbaum'13]
- Open question: $N^{\log N} \xrightarrow{7} N^{o(\log N)}$



Given the multiplication tables of two groups of finite order N, determine whether they are isomorphic.

- First algorithm: $N^{\log N+O(1)}$ time attributed to Tarjan [Miller'78]
- Best known algorithm: $N^{\frac{1}{4} \log N + O(1)}$ time [Rosenbaum'13]
- Open question: $N^{\log N} \xrightarrow{?} N^{o(\log N)}$



Group Isomorphism vs. Graph Isomorphism

Similarity

- Both are extensively studied since 1970s.
- Both are neither known to be in P nor to be NP-complete.
- Best algorithms for both problems have a quasi-polynomial running time.

Differences



Group Isomorphism vs. Graph Isomorphism

Similarity

- Both are extensively studied since 1970s.
- Both are neither known to be in **P** nor to be **NP-complete**.
- Best algorithms for both problems have a quasi-polynomial running time.

Differences



- Both are extensively studied since 1970s.
- Both are neither known to be in P nor to be NP-complete.
- Best algorithms for both problems have a quasi-polynomial running time.

Differences



- Both are extensively studied since 1970s.
- Both are neither known to be in P nor to be NP-complete.
- Best algorithms for both problems have a quasi-polynomial running time.

Differences

	Group Iso	Graph Iso
Natural bound	$N^{\log N + O(1)}$ [Miller'78]	N!
Best known bound	$N^{\frac{1}{4}\log N+O(1)}$ [Rosenbaum'13]	$N^{O((\log M)^{\circ})}$ [Babai'17]

GROUP ISO blocks us from an $N^{o(\log N)}$ time algorithm for GRAPH ISO [Babai'17]!



- Both are extensively studied since 1970s.
- Both are neither known to be in P nor to be NP-complete.
- Best algorithms for both problems have a quasi-polynomial running time.

Differences

	Group Iso	Graph Iso
Natural bound	$N^{\log N + O(1)}$ [Miller'78]	N!
Best known bound	$N^{\frac{1}{4}\log N+O(1)}$ [Rosenbaum'13]	$N^{O((\log M)^{\circ})}$ [Babai'17]

GROUP ISO blocks us from an $N^{o(\log N)}$ time algorithm for GRAPH ISO [Babai'17]!



- Both are extensively studied since 1970s.
- Both are neither known to be in P nor to be NP-complete.
- Best algorithms for both problems have a quasi-polynomial running time.

Differences

	Group Iso	Graph Iso
Natural bound	$N^{\log N + O(1)}$ [Miller'78]	N!
Best known bound	$N^{\frac{1}{4}\log N+O(1)}$ [Rosenbaum'13]	$N^{O((\log N)^c)}$ [Babai'17]

GROUP ISO blocks us from an N^{o(log N)} time algorithm for GRAPH ISO [Babai'17]!



Note that c > 1 in Babai's algorithm.

- Both are extensively studied since 1970s.
- Both are neither known to be in P nor to be NP-complete.
- Best algorithms for both problems have a quasi-polynomial running time.

Differences

	Group Iso	Graph Iso
Natural bound	$N^{\log N + O(1)}$ [Miller'78]	N!
Best known bound	$N^{\frac{1}{4}\log N+O(1)}$ [Rosenbaum'13]	$N^{O((\log N)^c)}$ [Babai'17]

GROUP ISO blocks us from an $N^{o(\log N)}$ time algorithm for GRAPH ISO [Babai'17]!

UTS:QSI

Note that c > 1 in Babai's algorithm.

• Theoretical computer science: complexity in the worst case

- Computational group theory: practical algorithms (as in Magma or GAP)
- Cryptography: protocols based on isomorphism problems



- Theoretical computer science: complexity in the worst case
- Computational group theory: practical algorithms (as in Magma or GAP)

• Cryptography: protocols based on isomorphism problems



- Theoretical computer science: complexity in the worst case
- Computational group theory: practical algorithms (as in Magma or GAP)
- Cryptography: protocols based on isomorphism problems
 - Several schemes have been submitted to the NIST call for post-quantum digital signatures, such as *ALTEQ*, *MEDS*, and *LESS*.



- Theoretical computer science: complexity in the worst case
- Computational group theory: practical algorithms (as in Magma or GAP)
- Cryptography: protocols based on isomorphism problems
 - Several schemes have been submitted to the NIST call for post-quantum digital signatures, such as *ALTEQ*, *MEDS*, and *LESS*.



- Theoretical computer science: complexity in the worst case
- Computational group theory: practical algorithms (as in Magma or GAP)
- Cryptography: protocols based on isomorphism problems
 - Several schemes have been submitted to the NIST call for post-quantum digital signatures, such as *ALTEQ*, *MEDS*, and *LESS*.

Recent breakthrough in GROUP ISO of a special class

Theorem (Sun'23)

Given two p-groups of class 2 and exponent p of order N, there exists an algorithm in time $N^{\tilde{O}((\log N)^{5/6})}$ to decide whether they are isomorphic.

Why this class of groups?

The isomorphism testing between p-groups of class 2 and exponent p is a major bottleneck for GROUP ISO.

Definition (*p*-groups of class 2 and exponent p).

For prime p, we say a p-group G is of class-2 and exponent p, if

- every $g \in G$ satisfies that $g^p = id$, and
- [G, [G, G]] only contains the identity element.

The isomorphism testing between p-groups of class 2 and exponent p can reduce to the isomorphism testing between two 3-tensors.
UTS:051

Recent breakthrough in GROUP ISO of a special class

Theorem (Sun'23)

Given two p-groups of class 2 and exponent p of order N, there exists an algorithm in time $N^{\tilde{O}((\log N)^{5/6})}$ to decide whether they are isomorphic.

Why this class of groups?

The isomorphism testing between p-groups of class 2 and exponent p is a major bottleneck for GROUP ISO.

Definition (p-groups of class 2 and exponent p).

For prime p, we say a p-group G is of class-2 and exponent p, if

- every $g \in G$ satisfies that $g^p = id$, and
- [G, [G, G]] only contains the identity element.

The isomorphism testing between p-groups of class 2 and exponent p can reduce to the isomorphism testing between two 3-tensors.



Given two p-groups of class 2 and exponent p of order N, there exists an algorithm in time $N^{\tilde{O}((\log N)^{5/6})}$ to decide whether they are isomorphic.

Why this class of groups?

• The isomorphism testing between *p*-groups of class 2 and exponent *p* is a major bottleneck for GROUP ISO.

Definition (p-groups of class 2 and exponent p).

For prime p, we say a p-group G is of class-2 and exponent p, if

- every $g \in G$ satisfies that $g^p = id$, and
- [G, [G, G]] only contains the identity element.

The isomorphism testing between p-groups of class 2 and exponent p can reduce to the isomorphism testing between two 3-tensors.
UTS:051

Given two p-groups of class 2 and exponent p of order N, there exists an algorithm in time $N^{\tilde{O}((\log N)^{5/6})}$ to decide whether they are isomorphic.

Why this class of groups?

1 The isomorphism testing between p-groups of class 2 and exponent p is a major bottleneck for GROUP ISO.

Definition (*p*-groups of class 2 and exponent p)

For prime p, we say a p-group G is of class-2 and exponent p, if

- every $g \in G$ satisfies that $g^p = id$, and
- [G, [G, G]] only contains the identity element.

The isomorphism testing between p-groups of class 2 and exponent p can reduce to the isomorphism testing between two 3-tensors.
UTS:051

Given two p-groups of class 2 and exponent p of order N, there exists an algorithm in time $N^{\tilde{O}((\log N)^{5/6})}$ to decide whether they are isomorphic.

Why this class of groups?

1 The isomorphism testing between p-groups of class 2 and exponent p is a major bottleneck for GROUP ISO.

Definition (*p*-groups of class 2 and exponent p)

For prime p, we say a p-group G is of class-2 and exponent p, if

- every $g \in G$ satisfies that $g^p = \mathrm{id}$, and
- [G, [G, G]] only contains the identity element.

The isomorphism testing between p-groups of class 2 and exponent p can reduce to the isomorphism testing between two 3-tensors.

Given two p-groups of class 2 and exponent p of order N, there exists an algorithm in time $N^{\tilde{O}((\log N)^{5/6})}$ to decide whether they are isomorphic.

Why this class of groups?

1 The isomorphism testing between p-groups of class 2 and exponent p is a major bottleneck for GROUP ISO.

Definition (*p*-groups of class 2 and exponent p)

For prime p, we say a p-group G is of class-2 and exponent p, if

- every $g \in G$ satisfies that $g^p = id$, and
- [G, [G, G]] only contains the identity element.

2 The isomorphism testing between p-groups of class 2 and exponent p can reduce to the isomorphism testing between two 3-tensors.
UTS:051

Tensor Isomorphism Problem

• Tensors are multi-way arrays, e.g., 2-tensor $A = (a_{i,j})_n$ is an $n \times n$ matrix:



• Similarly, 3-tensors are arrays with 3 indices, like a cube with matrix slices:



 More generally, we can define *d*-tensors, but *d*-TENSOR ISO is as hard as 3-TENSOR ISO. [Grochow-Qiao'23]

Tensor Isomorphism Problem

• Tensors are multi-way arrays, e.g., 2-tensor $A = (a_{i,j})_n$ is an $n \times n$ matrix:



• Similarly, **3-tensors** are arrays with 3 indices, like a cube with matrix slices:



 More generally, we can define d-tensors, but d-TENSOR ISO is as hard as B-TENSOR ISO. [Grochow-Qiao'23]
 UTS:QSI

Tensor Isomorphism Problem

• Tensors are multi-way arrays, e.g., 2-tensor $A = (a_{i,j})_n$ is an $n \times n$ matrix:



• Similarly, 3-tensors are arrays with 3 indices, like a cube with matrix slices:



• More generally, we can define *d*-tensors, but *d*-TENSOR ISO is as hard as **3**-TENSOR ISO. [Grochow-Qiao'23] Isomorphism for 3-tensors under three invertible matrices P, Q, and S:
























Tensor Isomorphism Problem

Definition (Linear span of matrices)

Let $\{B_i : i \in [n]\}$ be a set of matrices over \mathbb{F}_q . Then

$$\operatorname{span}\{B_i : i \in [n]\} := \{\sum_{i=1}^n c_i B_i : c_i \in \mathbb{F}_q\}.$$

(Equivalence testing of 3-tensors)

Given two $n \times n \times n$ tensors over \mathbb{F}_q whose frontal slices are $\{A_i : i \in [n]\}$ and $\{B_i : i \in [n]\}$, respectively. Determine if they are equivalent, i.e., if there exist two invertible matrices P and Q such that

 $\operatorname{span}\{B_i: i \in [n]\} = \operatorname{span}\{PA_iQ: i \in [n]\}.$

(Congruence testing of 3-tensors)

Given two $n \times n \times n$ tensors over \mathbb{F}_q whose frontal slices are $\{A_i : i \in [n]\}$ and $\{B_i : i \in [n]\}$, respectively. Determine if they are congruent, i.e., if there exist one invertible matrix T such that

 $\operatorname{span}\{B_i: i \in [n]\} = \operatorname{span}\{T^{\mathsf{t}}A_iT: i \in [n]\}.$

Tensor Isomorphism Problem

Definition (Linear span of matrices)

Let $\{B_i : i \in [n]\}$ be a set of matrices over \mathbb{F}_q . Then

$$\text{span}\{B_i : i \in [n]\} := \{\sum_{i=1}^n c_i B_i : c_i \in \mathbb{F}_q\}.$$

Problem (Equivalence testing of 3-tensors)

Given two $n \times n \times n$ tensors over \mathbb{F}_q whose frontal slices are $\{A_i : i \in [n]\}$ and $\{B_i : i \in [n]\}$, respectively. Determine if they are equivalent, i.e., if there exist two invertible matrices P and Q such that

 $\operatorname{span}\{B_i : i \in [n]\} = \operatorname{span}\{PA_iQ : i \in [n]\}.$

Problem (Congruence testing of 3-tensors)

Given two $n \times n \times n$ tensors over \mathbb{F}_q whose frontal slices are $\{A_i : i \in [n]\}$ and $\{B_i : i \in [n]\}$, respectively. Determine if they are congruent, i.e., if there exist one invertible matrix T such that

 $\operatorname{span}\{B_i : i \in [n]\} = \operatorname{span}\{T^t A_i T : i \in [n]\}.$

Tensor Isomorphism Problem

Definition (Linear span of matrices)

Let $\{B_i : i \in [n]\}$ be a set of matrices over \mathbb{F}_q . Then

$$\text{span}\{B_i : i \in [n]\} := \{\sum_{i=1}^n c_i B_i : c_i \in \mathbb{F}_q\}.$$

Problem (Equivalence testing of 3-tensors)

Given two $n \times n \times n$ tensors over \mathbb{F}_q whose frontal slices are $\{A_i : i \in [n]\}$ and $\{B_i : i \in [n]\}$, respectively. Determine if they are equivalent, i.e., if there exist two invertible matrices P and Q such that

 $\operatorname{span}\{B_i : i \in [n]\} = \operatorname{span}\{PA_iQ : i \in [n]\}.$

Problem (Congruence testing of 3-tensors)

Given two $n \times n \times n$ tensors over \mathbb{F}_q whose frontal slices are $\{A_i : i \in [n]\}$ and $\{B_i : i \in [n]\}$, respectively. Determine if they are congruent, i.e., if there exist one invertible matrix T such that

 $\operatorname{span}\{B_i: i \in [n]\} = \operatorname{span}\{T^{\mathsf{t}}A_i T: i \in [n]\}.$



Theorem (Baer's correspondence)





Theorem (Baer's correspondence)





Theorem (Baer's correspondence)





Theorem (Baer's correspondence)





Theorem (Baer's correspondence)





Theorem (Baer's correspondence)





Theorem (Baer's correspondence)



- Natural upper bound: $q^{O(n^2)}$ (known since at least 1970's)
- Sun's breakthrough: $q^{O(n^{1,\circ} \cdot \log q)}$ [Sun'23]
- Our improvement:



invertible matrices



- Natural upper bound: $q^{O(n^2)}$ (known since at least 1970's)
- Sun's breakthrough: $q^{O(n^{1.8} \cdot \log q)}$ [Sun'23]

• Our improvement:



- Natural upper bound: $q^{O(n^2)}$ (known since at least 1970's)
- Sun's breakthrough: $q^{O(n^{1.8} \cdot \log q)}$ [Sun'23]
 - addressed the congruence testing of skew-symmetric 3-tensors.
 - Our improvement



- Natural upper bound: $q^{O(n^2)}$ (known since at least 1970's)
- Sun's breakthrough: $q^{O(n^{1.8} \cdot \log q)}$ [Sun'23]
 - addressed the congruence testing of skew-symmetric 3-tensors.
 - improved the isomorphism testing of p-groups of class 2 and exponent p.

• Our improvement:



- Natural upper bound: $q^{O(n^2)}$ (known since at least 1970's)
- Sun's breakthrough: $q^{O(n^{1.8} \cdot \log q)}$ [Sun'23]
 - addressed a special 3-TENSOR ISO problem reducible to our problem.

• Our improvement: for the equivalence testing of general 3-tensors





- Natural upper bound: $q^{O(n^2)}$ (known since at least 1970's)
- Sun's breakthrough: $q^{O(n^{1.8} \cdot \log q)}$ [Sun'23]
 - addressed a special 3-TENSOR ISO problem reducible to our problem.
 - improved the isomorphism testing of a subclass of our underlying groups.*
- Our improvement: 100000 for the equivalence testing of general 3-tensors



*We extend to *p*-groups of Frattini class 2 by the results in [Higman'60, Grochow-Qiao'24].

UTS:051

- Natural upper bound: $q^{O(n^2)}$ (known since at least 1970's)
- Sun's breakthrough: $q^{O(n^{1.8} \cdot \log q)}$ [Sun'23]
 - addressed a special 3-TENSOR ISO problem reducible to our problem.
 - $\bullet\,$ improved the isomorphism testing of a subclass of our underlying groups.*
- Our improvement: $q^{\tilde{O}(n^{1.5})}$ for the equivalence testing of general 3-tensors



^{*}We extend to p-groups of Frattini class 2 by the results in [Higman'60, Grochow-Qiao'24].

UTS:05



 $\operatorname{span}\{PA_1Q,\cdots,PA_nQ\}=\operatorname{span}\{B_1,\cdots,B_n\}$







UTS:05











• We first make the 3-tensors in a semi-canonical form by applying P, Q and S, and then construct matrix tuples from the semi-canonical form by applying P.

- The margins are supposed to be small, to reduce the cost of further enumeration of the possible action matrices.
- The margin for the third direction, while can be large, is 'fixed' somehow.





- We first make the 3-tensors in a semi-canonical form by applying *P*, *Q* and *S*, and then construct matrix tuples from the semi-canonical 3-tensors.
- The margins are supposed to be small, to reduce the cost of further enumeration of the possible action matrices.
- The margin for the third direction, while can be large, is 'fixed' somehow.





- We first make the 3-tensors in a semi-canonical form by applying *P*, *Q* and *S*, and then construct matrix tuples from the semi-canonical 3-tensors.
- The margins are supposed to be small, to reduce the cost of further enumeration of the possible action matrices.
- The margin for the third direction, while can be large, is 'fixed' somehow.





- We first make the 3-tensors in a semi-canonical form by applying *P*, *Q* and *S*, and then construct matrix tuples from the semi-canonical 3-tensors.
- The margins are supposed to be small, to reduce the cost of further enumeration of the possible action matrices.
- The margin for the third direction, while can be large, is 'fixed' somehow.



- 1. Refinement: fix rear slices and leave the frontal to span a low-rank space
- 2. Low-rank characterization: make a big zero block on the low-rank slices





- 1. Refinement: fix rear slices and leave the frontal to span a low-rank space*
- 2. Low-rank characterization: make a big zero block on the low-rank slices



^{*}A linear space of matrices is of low rank, if every matrix in it is of low rank.



- 1. Refinement: fix rear slices and leave the frontal to span a low-rank space*
- 2. Low-rank characterization: make a big zero block on the low-rank slices



^{*}A linear space of matrices is of low rank, if every matrix in it is of low rank.



- 1. Refinement: fix rear slices and leave the frontal to span a low-rank space*
- 2. Low-rank characterization: make a big zero block on the low-rank slices



^{*}A linear space of matrices is of low rank, if every matrix in it is of low rank.

A special case: canonicalization by compression



- Assume we can apply $L \in \operatorname{GL}(s \times n, \mathbb{F}_q)$ and $R \in \operatorname{GL}(n \times s, \mathbb{F}_q)$ such that $LA_1R, \dots, LA_nR \in \operatorname{M}(s \times s, \mathbb{F}_q)$ are linearly independent.
- Then there is a quick algorithm to test the isomorphism between two 3-tensors A and B.

• What if LAR = 0 for some non-zero $A \in \text{span}\{A_i : i \in [n]\}$?




- Assume we can apply $L \in \operatorname{GL}(s \times n, \mathbb{F}_q)$ and $R \in \operatorname{GL}(n \times s, \mathbb{F}_q)$ such that $LA_1R, \cdots, LA_nR \in \operatorname{M}(s \times s, \mathbb{F}_q)$ are linearly independent.
- $\bullet\,$ Then there is a quick algorithm to test the isomorphism between two 3-tensors A and $B.\,$





- Assume we can apply $L \in \operatorname{GL}(s \times n, \mathbb{F}_q)$ and $R \in \operatorname{GL}(n \times s, \mathbb{F}_q)$ such that $LA_1R, \cdots, LA_nR \in \operatorname{M}(s \times s, \mathbb{F}_q)$ are linearly independent.
- $\bullet\,$ Then there is a quick algorithm to test the isomorphism between two 3-tensors A and $B.\,$
 - Compute the canonical basis of *LAR*.
 - Enumerate such matrices L' and R' for B, which costs $q^{O(ns)}$
 - Compute the canonical basis of L'BR' and compare it to that of LAR.
 - The correspondence between L, L' and R, R' gives the desired isomorphism.

UTSIOS



- Assume we can apply $L \in \operatorname{GL}(s \times n, \mathbb{F}_q)$ and $R \in \operatorname{GL}(n \times s, \mathbb{F}_q)$ such that $LA_1R, \cdots, LA_nR \in \operatorname{M}(s \times s, \mathbb{F}_q)$ are linearly independent.
- $\bullet\,$ Then there is a quick algorithm to test the isomorphism between two 3-tensors A and $B.\,$
 - Compute the canonical basis of *LAR*.
 - Enumerate such matrices L' and R' for B, which costs $q^{O(ns)}$.
 - Compute the canonical basis of L'BR' and compare it to that of LAR.
 - The correspondence between L, L' and R, R' gives the desired isomorphism.



- Assume we can apply $L \in \operatorname{GL}(s \times n, \mathbb{F}_q)$ and $R \in \operatorname{GL}(n \times s, \mathbb{F}_q)$ such that $LA_1R, \cdots, LA_nR \in \operatorname{M}(s \times s, \mathbb{F}_q)$ are linearly independent.
- $\bullet\,$ Then there is a quick algorithm to test the isomorphism between two 3-tensors A and $B.\,$
 - Compute the canonical basis of *LAR*.
 - Enumerate such matrices L' and R' for B, which costs $q^{O(ns)}$.
 - Compute the canonical basis of L'BR' and compare it to that of LAR.
 - The correspondence between L, L' and R, R' gives the desired isomorphism.





- Assume we can apply $L \in \operatorname{GL}(s \times n, \mathbb{F}_q)$ and $R \in \operatorname{GL}(n \times s, \mathbb{F}_q)$ such that $LA_1R, \cdots, LA_nR \in \operatorname{M}(s \times s, \mathbb{F}_q)$ are linearly independent.
- $\bullet\,$ Then there is a quick algorithm to test the isomorphism between two 3-tensors A and $B.\,$
 - Compute the canonical basis of *LAR*.
 - Enumerate such matrices L' and R' for B, which costs $q^{O(ns)}$.
 - Compute the canonical basis of L'BR' and compare it to that of LAR.
 - The correspondence between L,L^\prime and R,R^\prime gives the desired isomorphism.



- Assume we can apply $L \in \operatorname{GL}(s \times n, \mathbb{F}_q)$ and $R \in \operatorname{GL}(n \times s, \mathbb{F}_q)$ such that $LA_1R, \cdots, LA_nR \in \operatorname{M}(s \times s, \mathbb{F}_q)$ are linearly independent.
- $\bullet\,$ Then there is a quick algorithm to test the isomorphism between two 3-tensors A and $B.\,$
 - Compute the canonical basis of *LAR*.
 - Enumerate such matrices L' and R' for B, which costs $q^{O(ns)}$.
 - Compute the canonical basis of L'BR' and compare it to that of LAR.
 - The correspondence between L,L^\prime and R,R^\prime gives the desired isomorphism.
- What if LAR = 0 for some non-zero $A \in \text{span}\{A_i : i \in [n]\}$?



- Given a 3-tensor A whose frontal slices span $\mathcal{A} \leq \mathrm{M}(n, \mathbb{F}_q)$.
- Basic idea: sort the basis matrices (subject to choices of L, R) such that

• Advantage: $\operatorname{Ker}_{L,R}(\mathcal{A})$ is a low-rank subspace with a high probability.





- Given a 3-tensor A whose frontal slices span $\mathcal{A} \leq \mathrm{M}(n, \mathbb{F}_q)$.
- Basic idea: sort the basis matrices (subject to choices of L, R) such that
- the remaining ones form a canonical basis of the quotient space A/Ker_{L,R}(A).
 Advantage: Ker_{L,R}(A) is a low-rank subspace with a high probability.





• Given a 3-tensor A whose frontal slices span $\mathcal{A} \leq \mathrm{M}(n, \mathbb{F}_q)$.

- Basic idea: sort the basis matrices (subject to choices of L, R) such that
 - the first ones span $\operatorname{Ker}_{L,R}(\mathcal{A}) := \operatorname{span}\{A \in \mathcal{A} \mid LAR = 0\}$, and

• the remaining ones form a canonical basis of the quotient space \mathcal{A} / Ker_{L,R}(\mathcal{A}). • Advantage: Ker_{L,R}(\mathcal{A}) is a low-rank subspace with a high probability.





- Given a 3-tensor A whose frontal slices span $\mathcal{A} \leq \mathrm{M}(n, \mathbb{F}_q)$.
- Basic idea: sort the basis matrices (subject to choices of L, R) such that
 - the first ones span $\operatorname{Ker}_{L,R}(\mathcal{A}) := \operatorname{span}\{A \in \mathcal{A} \mid LAR = 0\}$, and
 - the remaining ones form a canonical basis of the quotient space $\mathcal{A}/\operatorname{Ker}_{L,R}(\mathcal{A})$.

• Advantage: Ker_{L,R}(\mathcal{A}) is a low-rank subspace with a high probability.



- Given a 3-tensor A whose frontal slices span $\mathcal{A} \leq \mathrm{M}(n, \mathbb{F}_q)$.
- Basic idea: sort the basis matrices (subject to choices of L, R) such that
 - the first ones span $\operatorname{Ker}_{L,R}(\mathcal{A}) := \operatorname{span}\{A \in \mathcal{A} \mid LAR = 0\}$, and
 - the remaining ones form a canonical basis of the quotient space $\mathcal{A}/\operatorname{Ker}_{L,R}(\mathcal{A})$.
- Advantage: $\operatorname{Ker}_{L,R}(\mathcal{A})$ is a low-rank subspace with a high probability.

Advantage: $\operatorname{Ker}_{L,R}(\mathcal{A})$ is a low-rank subspace with a high probability.

Let $\mathcal{A} \leq \mathrm{M}(n, \mathbb{F}_q)$ be a matrix subspace of dimension n. Then with at least probability of $1 - \frac{1}{q}$, $\mathrm{Ker}_{L,R}(\mathcal{A})$ consists of matrices of rank $\leq r$ for uniformly randomly sampled $L \in \mathrm{M}(s \times n, \mathbb{F}_q)$ and $R \in \mathrm{M}(n \times s, \mathbb{F}_q)$.



Advantage: $\operatorname{Ker}_{L,R}(\mathcal{A})$ is a low-rank subspace with a high probability.

Lemma (Ivanyos-Mendoza-Qiao-Sun-Zhang'24)

Let $\mathcal{A} \leq M(n, \mathbb{F}_q)$ be a matrix subspace of dimension n. Fix some $r \in [n]$, and let

$$s = \lceil 3 \cdot \max\{\frac{n}{r}, r\} \rceil.$$

Then with at least probability of $1 - \frac{1}{q^r}$, $\operatorname{Ker}_{L,R}(\mathcal{A})$ consists of matrices of rank $\leq r$ for uniformly randomly sampled $L \in \operatorname{M}(s \times n, \mathbb{F}_q)$ and $R \in \operatorname{M}(n \times s, \mathbb{F}_q)$.



Advantage: $\operatorname{Ker}_{L,R}(\mathcal{A})$ is a low-rank subspace with a high probability.

Lemma (Ivanyos-Mendoza-Qiao-Sun-Zhang'24)

Let $\mathcal{A} \leq M(n, \mathbb{F}_q)$ be a matrix subspace of dimension n. Let $r = \sqrt{n}$ and

 $s = O(\sqrt{n}).$

Then with at least probability of $1 - \frac{1}{q^r}$, $\operatorname{Ker}_{L,R}(\mathcal{A})$ consists of matrices of rank $\leq r$ for uniformly randomly sampled $L \in \operatorname{M}(s \times n, \mathbb{F}_q)$ and $R \in \operatorname{M}(n \times s, \mathbb{F}_q)$.



Advantage: $\operatorname{Ker}_{L,R}(\mathcal{A})$ is a low-rank subspace with a high probability.

Lemma (Ivanyos-Mendoza-Qiao-Sun-Zhang'24)

Let $\mathcal{A} \leq M(n, \mathbb{F}_q)$ be a matrix subspace of dimension n. Let $r = \sqrt{n}$ and

 $s = O(\sqrt{n}).$

Then with at least probability of $1 - \frac{1}{q^r}$, $\operatorname{Ker}_{L,R}(\mathcal{A})$ consists of matrices of rank $\leq r$ for uniformly randomly sampled $L \in \operatorname{M}(s \times n, \mathbb{F}_q)$ and $R \in \operatorname{M}(n \times s, \mathbb{F}_q)$.

Again, to find L', R' such that B is refined correspondingly to A, we still need to enumerate all L', R' in the same size, which costs $q^{O(ns)}$.



Advantage: $\operatorname{Ker}_{L,R}(\mathcal{A})$ is a low-rank subspace with a high probability.

Lemma (Ivanyos-Mendoza-Qiao-Sun-Zhang'24)

Let $\mathcal{A} \leq M(n, \mathbb{F}_q)$ be a matrix subspace of dimension n. Let $r = \sqrt{n}$ and

 $s = O(\sqrt{n}).$

Then with at least probability of $1 - \frac{1}{q^r}$, $\operatorname{Ker}_{L,R}(\mathcal{A})$ consists of matrices of rank $\leq r$ for uniformly randomly sampled $L \in \operatorname{M}(s \times n, \mathbb{F}_q)$ and $R \in \operatorname{M}(n \times s, \mathbb{F}_q)$.













d + f = O(r)over field of order $\geq r + 1$ [Flanders'62]





```
d + f = O(r^2)<br/>[Sun'23]
```









- By [Ivanyos-Qiao-Subrahmanyam'18], we can canonicalize the zero block in this case.
- $O(r \log r)$ is obtained from our proof of an inequality between the maximal rank and the non-commutative rank in matrix spaces.





- By [Ivanyos-Qiao-Subrahmanyam'18], we can canonicalize the zero block in this case.
- $O(r \log r)$ is obtained from our proof of an inequality between the maximal rank and the non-commutative rank in matrix spaces.





- By [Ivanyos-Qiao-Subrahmanyam'18], we can canonicalize the zero block in this case.
- $O(r \log r)$ is obtained from our proof of an inequality between the maximal rank and the non-commutative rank in matrix spaces.





- By [Ivanyos-Qiao-Subrahmanyam'18], we can canonicalize the zero block in this case.
- $O(r \log r)$ is obtained from our proof of an inequality between the maximal rank and the non-commutative rank in matrix spaces.





 $d+f=\tilde{O}(\sqrt{n})$

[Ivanyos-Mendoza-Qiao-Sun-Zhang'24]

- By [Ivanyos-Qiao-Subrahmanyam'18], we can canonicalize the zero block in this case.
- $O(r \log r)$ is obtained from our proof of an inequality between the maximal rank and the non-commutative rank in matrix spaces.













Upon enumeration which costs $q^{O(n)}$

$$P = \begin{bmatrix} P_1 & P_2 \\ P_1 & P_2 \\ P_3 & P_3 \end{bmatrix} \qquad Q = \begin{bmatrix} Q_1 & Q_2 \\ Q_1 & Q_2 \\ P_3 & P_3 \end{bmatrix} \qquad S = \begin{bmatrix} S_1 & S_2 \\ S_1 & P_3 \\ P_1 & P_2 \\ P_2 & P_2 \\ P_1 & P_2 \\ P_2 & P_2 \\ P_1 & P_2 \\ P_1 & P_2 \\ P_2 & P_2 \\ P_2 & P_2 \\ P_1 & P_2 \\ P_2 &$$





Upon enumeration which costs $q^{O(r)}$

$$P = \begin{bmatrix} P_1 & P_2 \\ P_1 & P_2 \\ P_3 & P_3 \end{bmatrix} \qquad Q = \begin{bmatrix} Q_1 & Q_2 \\ Q_2 & P_3 \\ Q_1 & Q_2 \\ Q_3 & P_4 \end{bmatrix} \qquad S = \begin{bmatrix} S_1 & S_2 \\ S_1 & S_2 \\ P_4 & P_4 \end{bmatrix}$$

















Some colorful slices may be transposed appropriately to match the action matrices.



Some colorful slices may be transposed appropriately to match the action matrices.

From 3-TENSOR ISO to (skew-symmetric) TUPLE ISO



 $\exists \text{ an invertible matrix } T \text{ s.t. } (T^{t}A_{1}T, \cdots, T^{t}A_{O(n)}T) = (B_{1}, \cdots, B_{O(n)}) \quad \underbrace{\mathsf{UTS:OSI}}_{T \text{ is conditioned in a special form, but it is still reducible to the general problem.}$
Theorem (Ivanyos-Qiao'19)

Given two skew-symmetric matrix tuples over \mathbb{F}_q , there exists a polynomialtime algorithm that decides whether they are congruent.

[Vanyos-Mendoza-Qiao-Sun-Zhang'24]

Given two $n \times n \times n$ tensors over \mathbb{F}_q , there exists an algorithm in time $q^{O(n^{1/2})}$ that decides whether they are equivalent.

Theorem (Ivanyos-Mendoza-Qiao-Sun-Zhang'24)

Given two p-groups of Frattini class 2 of order N, there exists an algorithm in time $N^{\overline{O}((\log N)^{1/2})}$ to decide whether they are isomorphic.



Theorem (Ivanyos-Qiao'19)

Given two skew-symmetric matrix tuples over \mathbb{F}_q , there exists a polynomialtime algorithm that decides whether they are congruent.

Theorem (Ivanyos-Mendoza-Qiao-Sun-Zhang'24)

Given two $n \times n \times n$ tensors over \mathbb{F}_q , there exists an algorithm in time $q^{\tilde{O}(n^{1.5})}$ that decides whether they are equivalent.

Theorem (Ivanyos-Mendoza-Qiao-Sun-Zhang'24)

Given two p-groups of Frattini class 2 of order N, there exists an algorithm in time $N^{\tilde{O}((\log N)^{1/2})}$ to decide whether they are isomorphic.



Theorem (Ivanyos-Qiao'19)

Given two skew-symmetric matrix tuples over \mathbb{F}_q , there exists a polynomialtime algorithm that decides whether they are congruent.

Theorem (Ivanyos-Mendoza-Qiao-Sun-Zhang'24)

Given two $n \times n \times n$ tensors over \mathbb{F}_q , there exists an algorithm in time $q^{\tilde{O}(n^{1.5})}$ that decides whether they are equivalent.

Theorem (Ivanyos-Mendoza-Qiao-Sun-Zhang'24)

Given two p-groups of Frattini class 2 of order N, there exists an algorithm in time $N^{\tilde{O}((\log N)^{1/2})}$ to decide whether they are isomorphic.



• Can we design a similar algorithm for 4-TENSOR ISO problem?

• Can we design more faster practical algorithms to break isomorphismbased cryptography protocols?

• Beyond isomorphism testing, 3-tensors themselves are intriguing objects.



- Can we design a similar algorithm for 4-TENSOR ISO problem?
- Can we design more faster practical algorithms to break isomorphismbased cryptography protocols?
 - [Narayanan-Qiao-Tang'24] made a heuristic one running in time $q^{n/2}$ for the average case of the equivalence testing of 3-tensors.
- Beyond isomorphism testing, 3-tensors themselves are intriguing objects.



- Can we design a similar algorithm for 4-TENSOR ISO problem?
- Can we design more faster practical algorithms to break isomorphismbased cryptography protocols?
 - [Narayanan-Qiao-Tang'24] made a heuristic one running in time $q^{n/2}$ for the average case of the equivalence testing of 3-tensors.

• Beyond isomorphism testing, 3-tensors themselves are intriguing objects.



- Can we design a similar algorithm for 4-TENSOR ISO problem?
- Can we design more faster practical algorithms to break isomorphismbased cryptography protocols?
 - [Narayanan-Qiao-Tang'24] made a heuristic one running in time $q^{n/2}$ for the average case of the equivalence testing of 3-tensors.
- Beyond isomorphism testing, 3-tensors themselves are intriguing objects.



- Can we design a similar algorithm for 4-TENSOR ISO problem?
- Can we design more faster practical algorithms to break isomorphismbased cryptography protocols?
 - [Narayanan-Qiao-Tang'24] made a heuristic one running in time $q^{n/2}$ for the average case of the equivalence testing of 3-tensors.
- Beyond isomorphism testing, 3-tensors themselves are intriguing objects. If anyone is interested, we can talk offline about two of my previous papers on the connections between properties of graphs and linear spaces of matrices [Li-Qiao-Wigderson-Wigderson-Zhang'22&23].

Thank you so much!

Please find the paper and slides available on my webpage:



https://www.chuanqizhang.com

